

**INSTRUCTION:**

This section consists of **FOUR (4)** questions. Answer **ALL** questions.

**ARAHAN:**

*Bahagian ini mengandungi EMPAT(4) soalan. Jawab SEMUA soalan.*

**QUESTION 1****SOALAN 1**

- CLO1  
C1
- a) i. State **THREE (3)** factors that affect the resistance of conductor materials.  
*Nyata TIGA (3) faktor yang mempengaruhi nilai kerintangan sesuatu pengalir.*
- [3 marks]  
[3 markah]
- CLO1  
C1
- ii. List **TWO (2)** types of the electrical circuits  
*Senaraikan DUA (2) jenis litar-litar elektrik*
- [2 marks]  
[2 markah]
- CLO2  
C2
- b) Express the value of resistance through the aluminum wire with a length of 100km and a diameter of 25cm if the supply is 100V. The resistivity of the wire is  $25.5\mu\Omega\text{m}$ .  
*Kirakan nilai rintangan melalui wayar aluminium dengan panjang 100km dan diameter 25cm jika bekalan 100V. Kerintangan wayar adalah  $25.5\mu\Omega\text{m}$ .*
- [9 marks]  
[9 markah]
- CLO2  
C3
- c) Given that  $R_1 = 4k\Omega$  and  $R_2 = 1.2k\Omega$ . Both resistors are connected in parallel and supplied with 40 V dc. Calculate these values:  
*Diberi nilai  $R_1 = 4k\Omega$  and  $R_2 = 1.2k\Omega$ . Kedua-dua perintang disambung secara selari dan mempunyai nilai voltan 40 V dc. Kirakan nilai:*
- i. The total resistance ( $R_T$ ) of the circuit  
*Jumlah rintangan ( $R_T$ ) di dalam litar*
- [4 marks]  
[4 markah]

- ii. The total current of the circuit

*Jumlah arus di dalam litar*

[3 marks]  
[3 markah]

- iii. The voltage drop at R1.

*Voltan susut pada perintang R1*

[1 marks]  
[1 markah]

- iv. Current flow through R2 by using current division method.

*Arus yang melalui perintang R2 dengan menggunakan kaedah pembahagian semasa.*

[3 marks]  
[3 markah]

## QUESTION 2

### SOALAN 2

CLO1  
C1

- a) List **FIVE (5)** effects of capacitor as an electrical component in a circuit.

*Senaraikan LIMA (5) kesan kapasitor sebagai komponen elektrik di dalam litar.*

[5 marks]  
[5 markah]

CLO1  
C2

- b) Compare the Single Phase System and Three Phase System in terms of definition, connection, waveform and application.

*Bandingkan sistem satu fasa dan sistem tiga fasa dari segi definisi, sambungan, bentuk gelombang dan aplikasi.*

[8 marks]  
[8 markah]

CLO2  
C3

- c) AC circuit 200V, 50 Hz connected in series with resistance  $40\Omega$ , inductance reactance  $20\Omega$  and capacitance reactance  $12\Omega$ . Calculate:

*Litar AC mempunyai 200V, 50Hz disambung secara siri dengan kerintangan  $40\Omega$ , regangan kearuhan  $20\Omega$  dan regangan kemuatan  $12\Omega$ . Kirakan*

- i. Impedance (Z)  
*Galangan*

[4 marks]  
[4 markah]

- ii. Current  
*Arus*

[2 marks]  
[2 markah]

- iii. Phase angle  
*Sudut fasa*

[3 marks]  
[3 markah]

- iv. Power factor  
*Faktor kuasa*

[3 marks]  
[3 markah]

### QUESTION 3

#### SOALAN 3

CLO1  
C1

- a) State the definition, symbol and unit for the following magnetic quantities:

*Nyatakan definisi, symbol dan kuantiti bagi kuantiti-kuantiti magnet berikut:*

- i. Magnetic Flux  
*Fluks magnet*

[2.5 marks]  
[2.5 markah]

- ii. Reluctance  
*Keengganan*

[2.5 marks]  
[2.5 markah]

CLO2  
C2

- b) A core of mild steel with loop shape has long average of 40cm and cross-sectional area  $2\text{cm}^2$ . The steel is wound with 1000 turns of coil and 4A current flowing through it. If given relative permeability is 1200. Express the value of:

*Teras keluli lembut dengan bentuk gelung mempunyai purata panjang 40cm dan luas keratan rentas  $2\text{cm}^2$ . Keluli itu dililit dengan 1000 lilitan gegelung dan arus 4A mengalir melaluinya. Jika diberi kebolehtelapan relatif ialah 1200. Nyatakan nilai bagi:*

- i. Magnetomotive force.

*Daya gerak magnet.*

[2 marks]  
[2 markah]

- ii. Magnetic field strength, H

*Kekuatan medan magnet*

[3 marks]  
[3 markah]

- iii. Flux density, B

*Ketumpatan Fluks magnet.*

[3 marks]  
[3 markah]

CLO2  
C3

- c) A steel bar of 500 mm length, 20 mm width and 60 mm height is wound with 450 turns wire. Through measurement, a magnetic field strength of 2500 At/m is established within the core that produced 9.5 mWb of magnetic flux. Calculate:

*Palang besi dengan panjang 500 mm, lebar 20 mm dan ketinggian 60 mm dililit dengan 450 putaran dawai. Melalui pengukuran, kekuatan medan magnet 2500 At/m ditetapkan dalam teras yang menghasilkan 9.5 mWb urat daya magnet. Kirakan:*

- i. Flux density.

*Ketumpatan Fluks magnet.*

[4 marks]  
[4 markah]

ii. Magnetomotive force.

*Daya gerak magnet.*

[2 marks]  
[2 markah]

iii. Current flow through the wire.

*Arus yang mengalir melalui wayar.*

[2 marks]  
[2 markah]

iv. Relative permeability of the steel core.

*Ketelapan relatif bagi teras besi.*

[2 marks]  
[2 markah]

v. Reluctance of the magnetic circuit.

*Keengganan bagi litar magnet.*

[2 marks]  
[2 markah]

#### QUESTION 4

#### SOALAN 4

CLO1  
C1

a) Define autotransformers and List **THREE (3)** advantages of Autotransformers

*Definisikan Autotransformer dan senaraikan **TIGA (3)** kelebihan Autotransformer*

[4 marks]  
[4 markah]

CLO2  
C3

- b) As an assistant engineer, you are given a task to calculate some quantities of a new machine with built-in transformer. The datasheet from the machine's manual book shows the following data:

Power Consumed: 70kVA

Voltage Input/output: 850 V / 225 V

Frequency: 60 Hz

Number of Input Winding: 800 turns

You are asked to calculate the following quantities:

*Sebagai seorang pembantu jurutera, anda diberi tugas untuk menentukan dan mengira beberapa perkara untuk mesin baru yang dilengkapi dengan transformer. Lembaran data daripada buku manual mesin menunjukkan data berikut:*

*Kuasa yang digunakan: 70kVA*

*Voltan masukan / keluaran: 850 V / 225 V*

*Frekuensi: 60 Hz*

*Bilangan lilitan masukan: 800 turns*

*Anda disuruh untuk mengira perkara berikut:*

- i. The number of secondary winding.

*Bilangan lilitan pada gegelung sekunder.*

[3 marks]

[3 markah]

- ii. The primary current

*Arus pada gegelung primer*

[3 marks]

[3 markah]

- iii. The secondary current

*Arus pada gegelung sekunder*

[3 marks]

[3 markah]

- iv. The maximum magnetic flux

*Nilai fluks maksima*

[3 marks]

[3 markah]

CLO2  
C2

(c) The frequency of the supply to the stator of 6 poles induction motor is 40 Hz and the rotor frequency is 2 Hz. Express the value of:

*Sebuah motor pearuh 6 kutub mempunyai frekuensi 40 Hz dan frekuensi rotor bernilai 2 Hz. Nyatakan nilai bagi:*

i. Synchronous speed

*Kelajuan segerak*

[3 marks]

[3 markah]

ii. Percent of slip

*Peratus gelinciran*

[4 marks]

[4 markah]

iii. Rotor speed

*Kelajuan rotor*

[2 marks]

[2 markah]

**SOALAN TAMAT**

# DJJ20053 – ELECTRICAL TECHNOLOGY

## FORMULA

| INTRODUCTION TO ELECTRICAL CIRCUITS  | ALTERNATING CURRENT CIRCUIT     | AC MACHINES                     |                                 |                                 |   |                             |                                 |                                 |   |   |                                 |                             |  |                   |              |                          |   |                                   |                   |              |                          |  |                                   |                   |                             |              |                                  |   |                                   |  |
|--|---------------------------------|---------------------------------|---------------------------------|---------------------------------|---|-----------------------------|---------------------------------|---------------------------------|---|---|---------------------------------|-----------------------------|--|-------------------|--------------|--------------------------|---|-----------------------------------|-------------------|--------------|--------------------------|--|-----------------------------------|-------------------|-----------------------------|--------------|----------------------------------|---|-----------------------------------|--|
| $R = \frac{\rho l}{A} \quad V = IR$ $P = IV \quad E = Pt$ $C = \frac{Q}{V}$ <p>KIRCHOFF'S LAW .<br/> <math>V_s = V_1 + V_2 + V_3</math><br/> <math>\Sigma I_{IN} = \Sigma I_{OUT}</math><br/> <math>I_1 = I_2 + I_3</math></p> <p><b>SERIES</b></p> <table border="1" style="width: 100%; border-collapse: collapse;"> <tr><td style="text-align: center;"><math>V_T = V_1 + V_2 + \dots + V_n</math></td></tr> <tr><td style="text-align: center;"><math>I_T = I_1 = I_2 = \dots = I_n</math></td></tr> <tr><td style="text-align: center;"><math>R_T = R_1 + R_2 + \dots + R_n</math></td></tr> <tr><td style="text-align: center;"><math>L_T = L_1 + L_2 + \dots + L_n</math></td></tr> <tr><td style="text-align: center;"><math>\frac{1}{C_T} = \frac{1}{C_1} + \frac{1}{C_2} + \dots + \frac{1}{C_n}</math></td></tr> <tr><td style="text-align: center;"><math>V_x = \frac{R_x}{R_T} V_T</math></td></tr> </table> <p><b>PARALLEL</b></p> <table border="1" style="width: 100%; border-collapse: collapse;"> <tr><td style="text-align: center;"><math>V_T = V_1 = V_2 = \dots = V_n</math></td></tr> <tr><td style="text-align: center;"><math>I_T = I_1 + I_2 + \dots + I_n</math></td></tr> <tr><td style="text-align: center;"><math>\frac{1}{R_T} = \frac{1}{R_1} + \frac{1}{R_2} + \dots + \frac{1}{R_n}</math></td></tr> <tr><td style="text-align: center;"><math>\frac{1}{L_T} = \frac{1}{L_1} + \frac{1}{L_2} + \dots + \frac{1}{L_n}</math></td></tr> <tr><td style="text-align: center;"><math>C_T = C_1 + C_2 + \dots + C_n</math></td></tr> <tr><td style="text-align: center;"><math>I_x = \frac{R_T}{R_x} I_T</math></td></tr> </table> | $V_T = V_1 + V_2 + \dots + V_n$ | $I_T = I_1 = I_2 = \dots = I_n$ | $R_T = R_1 + R_2 + \dots + R_n$ | $L_T = L_1 + L_2 + \dots + L_n$ | $\frac{1}{C_T} = \frac{1}{C_1} + \frac{1}{C_2} + \dots + \frac{1}{C_n}$ | $V_x = \frac{R_x}{R_T} V_T$ | $V_T = V_1 = V_2 = \dots = V_n$ | $I_T = I_1 + I_2 + \dots + I_n$ | $\frac{1}{R_T} = \frac{1}{R_1} + \frac{1}{R_2} + \dots + \frac{1}{R_n}$ | $\frac{1}{L_T} = \frac{1}{L_1} + \frac{1}{L_2} + \dots + \frac{1}{L_n}$ | $C_T = C_1 + C_2 + \dots + C_n$ | $I_x = \frac{R_T}{R_x} I_T$ | <p><b>RL CIRCUIT</b></p> <table border="1" style="width: 100%; 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| $V_T = V_1 + V_2 + \dots + V_n$  |                                 |                                 |                                 |                                 |   |                             |                                 |                                 |   |   |                                 |                             |  |                   |              |                          |   |                                   |                   |              |                          |  |                                   |                   |                             |              |                                  |   |                                   |  |
| $I_T = I_1 = I_2 = \dots = I_n$  |                                 |                                 |                                 |                                 |   |                             |                                 |                                 |   |   |                                 |                             |  |                   |              |                          |   |                                   |                   |              |                          |  |                                   |                   |                             |              |                                  |   |                                   |  |
| $R_T = R_1 + R_2 + \dots + R_n$  |                                 |                                 |                                 |                                 |   |                             |                                 |                                 |   |   |                                 |                             |  |                   |              |                          |   |                                   |                   |              |                          |  |                                   |                   |                             |              |                                  |   |                                   |  |
| $L_T = L_1 + L_2 + \dots + L_n$  |                                 |                                 |                                 |                                 |   |                             |                                 |                                 |   |   |                                 |                             |  |                   |              |                          |   |                                   |                   |              |                          |  |                                   |                   |                             |              |                                  |   |                                   |  |
| $\frac{1}{C_T} = \frac{1}{C_1} + \frac{1}{C_2} + \dots + \frac{1}{C_n}$  |                                 |                                 |                                 |                                 |   |                             |                                 |                                 |   |   |                                 |                             |  |                   |              |                          |   |                                   |                   |              |                          |  |                                   |                   |                             |              |                                  |   |                                   |  |
| $V_x = \frac{R_x}{R_T} V_T$  |                                 |                                 |                                 |                                 |   |                             |                                 |                                 |   |   |                                 |                             |  |                   |              |                          |   |                                   |                   |              |                          |  |                                   |                   |                             |              |                                  |   |                                   |  |
| $V_T = V_1 = V_2 = \dots = V_n$  |                                 |                                 |                                 |                                 |   |                             |                                 |                                 |   |   |                                 |                             |  |                   |              |                          |   |                                   |                   |              |                          |  |                                   |                   |                             |              |                                  |   |                                   |  |
| $I_T = I_1 + I_2 + \dots + I_n$  |                                 |                                 |                                 |                                 |   |                             |                                 |                                 |   |   |                                 |                             |  |                   |              |                          |   |                                   |                   |              |                          |  |                                   |                   |                             |              |                                  |   |                                   |  |
| $\frac{1}{R_T} = \frac{1}{R_1} + \frac{1}{R_2} + \dots + \frac{1}{R_n}$  |                                 |                                 |                                 |                                 |   |                             |                                 |                                 |   |   |                                 |                             |  |                   |              |                          |   |                                   |                   |              |                          |  |                                   |                   |                             |              |                                  |   |                                   |  |
| $\frac{1}{L_T} = \frac{1}{L_1} + \frac{1}{L_2} + \dots + \frac{1}{L_n}$  |                                 |                                 |                                 |                                 |   |                             |                                 |                                 |   |   |                                 |                             |  |                   |              |                          |   |                                   |                   |              |                          |  |                                   |                   |                             |              |                                  |   |                                   |  |
| $C_T = C_1 + C_2 + \dots + C_n$  |                                 |                                 |                                 |                                 |   |                             |                                 |                                 |   |   |                                 |                             |  |                   |              |                          |   |                                   |                   |              |                          |  |                                   |                   |                             |              |                                  |   |                                   |  |
| $I_x = \frac{R_T}{R_x} I_T$  |                                 |                                 |                                 |                                 |   |                             |                                 |                                 |   |   |                                 |                             |  |                   |              |                          |   |                                   |                   |              |                          |  |                                   |                   |                             |              |                                  |   |                                   |  |
| $I = \frac{V}{Z}$  |                                 |                                 |                                 |                                 |   |                             |                                 |                                 |   |   |                                 |                             |  |                   |              |                          |   |                                   |                   |              |                          |  |                                   |                   |                             |              |                                  |   |                                   |  |
| $V_L = IX_L$   |                                 |                                 |                                 |                                 |   |                             |                                 |                                 |   |   |                                 |                             |  |                   |              |                          |   |                                   |                   |              |                          |  |                                   |                   |                             |              |                                  |   |                                   |  |
| $Z = \sqrt{R^2 + X_L^2}$   |                                 |                                 |                                 |                                 |   |                             |                                 |                                 |   |   |                                 |                             |  |                   |              |                          |   |                                   |                   |              |                          |  |                                   |                   |                             |              |                                  |   |                                   |  |
| $\theta = \tan^{-1} \left[ \frac{X_L}{R} \right]$  |                                 |                                 |                                 |                                 |   |                             |                                 |                                 |   |   |                                 |                             |  |                   |              |                          |   |                                   |                   |              |                          |  |                                   |                   |                             |              |                                  |   |                                   |  |
| $\text{Cos} \theta = \frac{R}{Z}$  |                                 |                                 |                                 |                                 |   |                             |                                 |                                 |   |   |                                 |                             |  |                   |              |                          |   |                                   |                   |              |                          |  |                                   |                   |                             |              |                                  |   |                                   |  |
| $I = \frac{V}{Z}$  |                                 |                                 |                                 |                                 |   |                             |                                 |                                 |   |   |                                 |                             |  |                   |              |                          |   |                                   |                   |              |                          |  |                                   |                   |                             |              |                                  |   |                                   |  |
| $V_C = IX_C$   |                                 |                                 |                                 |                                 |   |                             |                                 |                                 |   |   |                                 |                             |  |                   |              |                          |   |                                   |                   |              |                          |  |                                   |                   |                             |              |                                  |   |                                   |  |
| $Z = \sqrt{R^2 + X_C^2}$   |                                 |                                 |                                 |                                 |   |                             |                                 |                                 |   |   |                                 |                             |  |                   |              |                          |   |                                   |                   |              |                          |  |                                   |                   |                             |              |                                  |   |                                   |  |
| $\theta = -\tan^{-1} \left[ \frac{X_C}{R} \right]$   |                                 |                                 |                                 |                                 |   |                             |                                 |                                 |   |   |                                 |                             |  |                   |              |                          |   |                                   |                   |              |                          |  |                                   |                   |                             |              |                                  |   |                                   |  |
| $\text{Cos} \theta = \frac{R}{Z}$  |                                 |                                 |                                 |                                 |   |                             |                                 |                                 |   |   |                                 |                             |  |                   |              |                          |   |                                   |                   |              |                          |  |                                   |                   |                             |              |                                  |   |                                   |  |
| $I = \frac{V}{Z}$  |                                 |                                 |                                 |                                 |   |                             |                                 |                                 |   |   |                                 |                             |  |                   |              |                          |   |                                   |                   |              |                          |  |                                   |                   |                             |              |                                  |   |                                   |  |
| $V_L = IX_L \quad V_R = IR$  |                                 |                                 |                                 |                                 |   |                             |                                 |                                 |   |   |                                 |                             |  |                   |              |                          |   |                                   |                   |              |                          |  |                                   |                   |                             |              |                                  |   |                                   |  |
| $V_C = IX_C$   |                                 |                                 |                                 |                                 |   |                             |                                 |                                 |   |   |                                 |                             |  |                   |              |                          |   |                                   |                   |              |                          |  |                                   |                   |                             |              |                                  |   |                                   |  |
| $Z = \sqrt{R^2 + (X_L - X_C)^2}$   |                                 |                                 |                                 |                                 |   |                             |                                 |                                 |   |   |                                 |                             |  |                   |              |                          |   |                                   |                   |              |                          |  |                                   |                   |                             |              |                                  |   |                                   |  |
| $\theta = \tan^{-1} \left[ \frac{X_L - X_C}{R} \right]$  |                                 |                                 |                                 |                                 |   |                             |                                 |                                 |   |   |                                 |                             |  |                   |              |                          |   |                                   |                   |              |                          |  |                                   |                   |                             |              |                                  |   |                                   |  |
| $\text{Cos} \theta = \frac{R}{Z}$  |                                 |                                 |                                 |                                 |   |                             |                                 |                                 |   |   |                                 |                             |  |                   |              |                          |   |                                   |                   |              |                          |  |                                   |                   |                             |              |                                  |   |                                   |  |